

# A derivative-free trust-region method for optimization on the ellipsoid

Pengcheng Xie

Academy of Mathematics and Systems Science, Chinese Academy of Sciences, University of Chinese Academy of Sciences

## Introduction

Most optimization methods depend on the derivative information about the objective function. However, in practice, we can not obtain the derivative information sometimes, and even the function evaluation is expensive. To optimize without using the derivative, derivative-free optimization (DFO) is proposed, which is also called black-box optimization (BBO). DFO aims to generate a sequence of iteration points  $\{\mathbf{x}_k\}$  to reach the minimizer with fewer function evaluations.

$$\min_{\mathbf{x} \in \mathbb{R}^n} F(\mathbf{x}), \text{ subject to } \mathbf{x}^\top \mathbf{A} \mathbf{x} + b = 0, \quad (1)$$

Our method is based on the model-based methods [1, 2, 3, 4, 5, 6, 7, 8]. In this paper, we discuss the equality constraint

$$\mathbf{x}^\top \mathbf{A} \mathbf{x} + b = 0, \quad (2)$$

where  $\mathbf{A} = \text{diag}\{a_1, a_2, \dots, a_n\}$ ,  $a_i > 0$ ,  $\forall i = 1, \dots, n$ , which denotes the ellipsoidal constraint. This kind of problem and the corresponding methods have wide use, such as the electronic structure calculations in materials sciences, of which the essence is solving an energy-minimizing problem with the orthogonality constraints. Besides, the linear eigenvalue problems are also special optimization problems with the orthogonality constraints.

## DFO Algorithm 1

For the ellipsoidal constraint (2), we denote  $g(\mathbf{x}) = \mathbf{x}^\top \mathbf{A} \mathbf{x} + b$ . The objective function with the Courant penalty function is  $P(\mathbf{x}, \sigma) = F(\mathbf{x}) + \sigma(g(\mathbf{x}))^2$ . Terminating condition:  $|g(\mathbf{x}_{k+1})| \leq \varepsilon$  or  $\|\mathbf{x}_k - \mathbf{x}_{k-1}\|_2 \leq \varepsilon$ .

### EC\_NEWUOA with the Courant penalty

- 1: Given  $\mathbf{x}_1 \in \mathbb{R}^n$ ,  $\sigma_1 > 0$ ,  $k := 1$ ,  $\varepsilon \geq 0$ .
- 2: Use the initial point  $\mathbf{x}_k$  and NEWUOA to solve  $\min_{\mathbf{x}} P(\mathbf{x}, \sigma_k)$ , and obtain  $\mathbf{x}_{k+1}$ .
- 3: If the terminating condition holds, then stop;  $\sigma_{k+1} = 10\sigma_k$ ,  $k := k + 1$ ; Go to step 2.

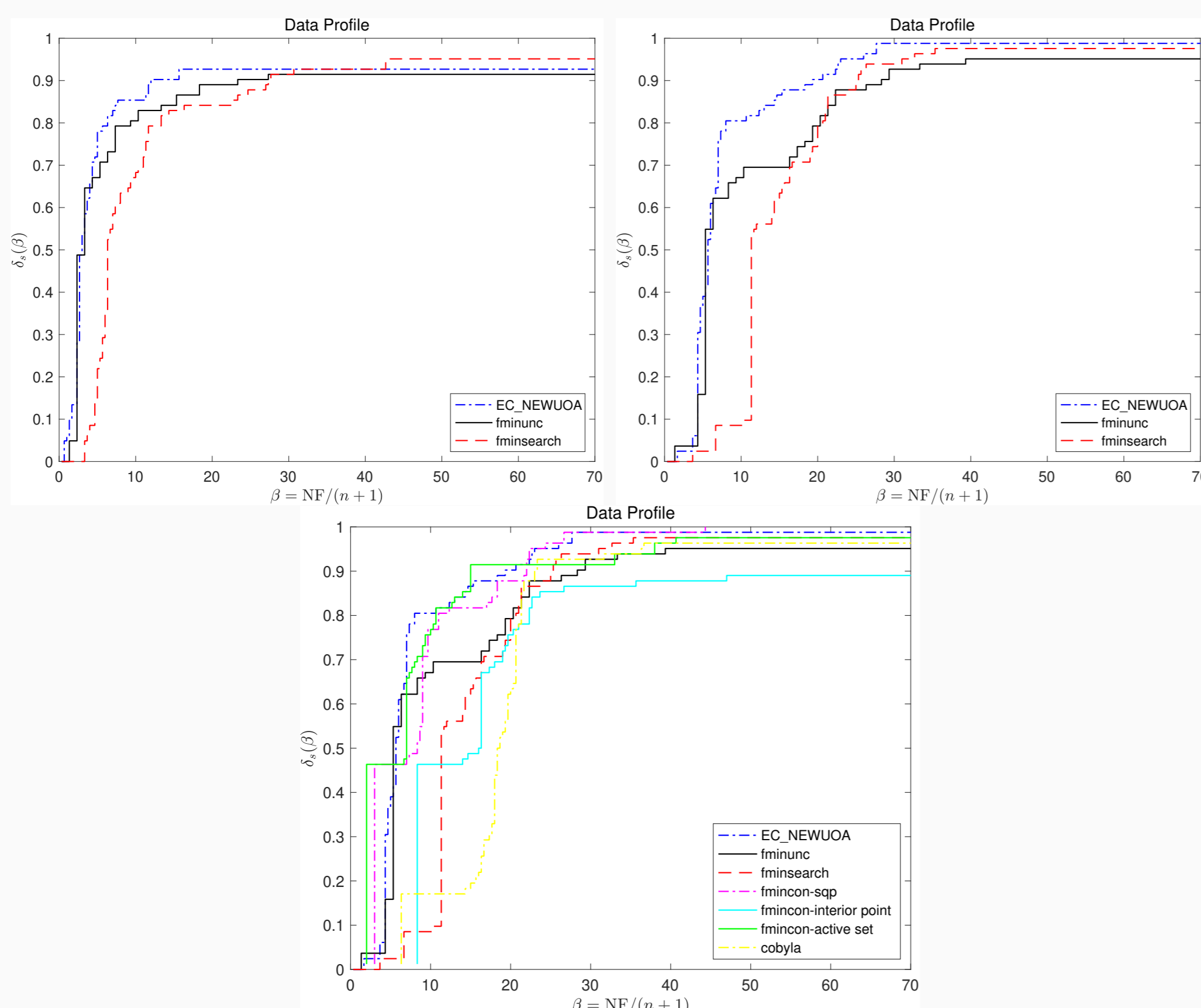
## DFO Algorithm 2

The objective function referring to the augmented Lagrangian method is  $L(\mathbf{x}, \lambda, \sigma) = F(\mathbf{x}) + \lambda g(\mathbf{x}) + \frac{1}{2}\sigma(g(\mathbf{x}))^2$ .

### EC\_NEWUOA using the augmented Lagrangian method

- 1: Given  $\mathbf{x}_1 \in \mathbb{R}^n$ ,  $\lambda_1 \in \mathbb{R}$ ,  $\lambda_1 \geq 0$ , and  $\varepsilon \geq 0$ ,  $\sigma_1 > 0$ ,  $k := 1$ .
- 2: Use the initial point  $\mathbf{x}_k$  and NEWUOA to solve  $\min_{\mathbf{x}} L(\mathbf{x}, \lambda_k, \sigma_k)$ , and obtain  $\mathbf{x}_{k+1}$ .
- 3: If the terminating condition holds, then stop;  $\lambda_{k+1} = \lambda_k + \sigma_k g(\mathbf{x}_{k+1})$ ;  $\sigma_{k+1} := 10\sigma_k$ ,  $k := k + 1$ ; Go to step 2.

## Numerica Results



## References

- [1] Powell M J D 2006 The NEWUOA software for unconstrained optimization without derivatives *Large-scale non-linear optimization* (New York, NY, USA: Springer) pp 255–297
- [2] Winfield D 1973 *IMA J. Appl. Math.* **12** 339–347
- [3] Powell M J D 2002 *Math. Program.* **92** 555–582
- [4] Powell M J D 2003 *Math. Program.* **97** 605–623
- [5] Xie P and Yuan Y x 2023 Least  $H^2$  norm updating quadratic interpolation model function for derivative-free trust-region algorithms (*Preprint* 2302.12017)
- [6] Xie P and Yuan Y x 2023 Derivative-free optimization with transformed objective functions (DFOTO) and the algorithm based on least Frobenius norm updating quadratic model (*Preprint* 2302.12021)
- [7] Li S, Xie P, Zhou Z, Wang Z, Li Z, Liang X and Qu B 2021 Simulation of interaction of folded waveguide space traveling wave tubes with derivative-free mixedinteger based NEWUOA algorithm *2021 7th Int. Conf. on Computer and Communications (Chengdu, China)* (Piscataway, NJ, USA: IEEE) pp 1215–1219
- [8] Conn A, Scheinberg K and Vicente L 2009 *SIAM J. Optim.* **20** 387–415